

A Co-Array Fortran Tutorial

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Outline

1. Philosophy of Co-Array Fortran
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1. The Co-Array Fortran Philosophy

The Co-Array Fortran Philosophy

- What is the smallest change required to make Fortran 90 an effective parallel language?
- How can this change be expressed so that it is intuitive and natural for Fortran programmers to understand?
- How can it be expressed so that existing compiler technology can implement it efficiently?

The Co-Array Fortran Standard

- Co-Array Fortran is defined by:
 - R.W. Numrich and J.K. Reid, “Co-Array Fortran for Parallel Programming”, ACM Fortran Forum, 17(2):1-31, 1998
- Additional information on the web:
 - www.co-array.org

Co-Array Fortran on the T3E

- CAF has been a supported feature of Fortran 90 since release 3.1
- f90 -Z src.f90
- mpexprun -n7 a.out

Non-Aligned Variables in SPMD Programs

- Addresses of arrays are on the local heap.
- Sizes and shapes are different on different program images.
- One processor knows nothing about another's memory layout.
- How can we exchange data between such non-aligned variables?

Some Solutions

- **MPI-1**
 - Elaborate system of buffers
 - Two-sided send/receive protocol
 - Programmer moves data between local buffers only.
- **SHMEM**
 - One-sided exchange between variables in COMMON
 - Programmer manages non-aligned addresses and computes offsets into arrays to compensate for different sizes and shapes
- **MPI-2**
 - Mimic SHMEM by exposing some of the buffer system
 - One-sided data exchange within predefined windows
 - Programmer manages addresses and offsets within the windows

Co-Array Fortran Solution

- Incorporate the SPMD Model into Fortran 95 itself
 - Mark variables with co-dimensions
 - Co-dimensions behave like normal dimensions
 - Co-dimensions match problem decomposition not necessarily hardware decomposition
- The underlying run-time system maps your problem decomposition onto specific hardware.
- One-sided data exchange between co-arrays
 - Compiler manages remote addresses, shapes and sizes

The CAF Programming Model

- Multiple images of the same program (SPMD)
 - Replicated text and data
 - The program is written in a sequential language.
 - An “object” has the same name in each image.
 - Extensions allow the programmer to point from an object in one image to the same object in another image.
 - The underlying run-time support system maintains a map among objects in different images.

2. Co-Arrays and Co-Dimensions

What is Co-Array Fortran?

- Co-Array Fortran (CAF) is a simple parallel extension to Fortran 90/95.
- It uses normal rounded brackets () to point to data in local memory.
- It uses square brackets [] to point to data in remote memory.
- Syntactic and semantic rules apply separately but equally to () and [].

What Do Co-dimensions Mean?

The declaration

real :: x(n)[p,q,*]

means

1. An array of length n is replicated across images.
2. The underlying system must build a map among these arrays.
3. The logical coordinate system for images is a three dimensional grid of size
4. (p,q,r) where r=num_images()/(pq)

Examples of Co-Array Declarations

```
real :: a(n)[*]
```

```
real ::b(n)[p,*]
```

```
real ::c(n,m)[p,q,*]
```

```
complex,dimension[*] :: z
```

```
integer,dimension(n)[*] :: index
```

```
real,allocatable,dimension(:)[:] :: w
```

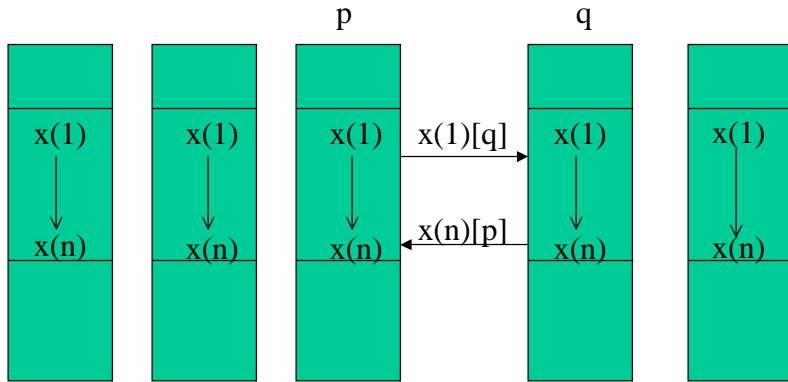
```
type(field), allocatable,dimension[:,:] :: maxwell
```

Communicating Between Co-Array “Objects”

```
y(:) = x(:)[p]  
myIndex(:) = index(:)  
yourIndex(:) = index(:)[you]  
yourField = maxwell[you]  
x(:)[q] = x(:) + x(:)[p]  
x(index(:)) = y[index(:)]
```

Absent co-dimension defaults to the local object.

CAF Memory Model



Example I: A PIC Code Fragment

```
type(Pstruct) particle(myMax),buffer(myMax)[*]
myCell = this_image(buffer)
yours = 0
do mine =1,myParticles
  If(particle(mine)%x > rightEdge) then
    yours = yours + 1
    buffer(yours)[myCell+1] = particle( mine)
  endif
enddo
```

Exercise: PIC Fragment

- Convince yourself that no synchronization is required for this one-dimensional problem.
- What kind of synchronization is required for the three-dimensional case?
- What are the tradeoffs between synchronization and memory usage?

3. Execution Model

The Execution Model (I)

- The number of images is fixed.
- This number can be retrieved at run-time.
 $\text{num_images}() \geq 1$
- Each image has its own index.
- This index can be retrieved at run-time.
 $1 \leq \text{this_image}() \leq \text{num_images}()$

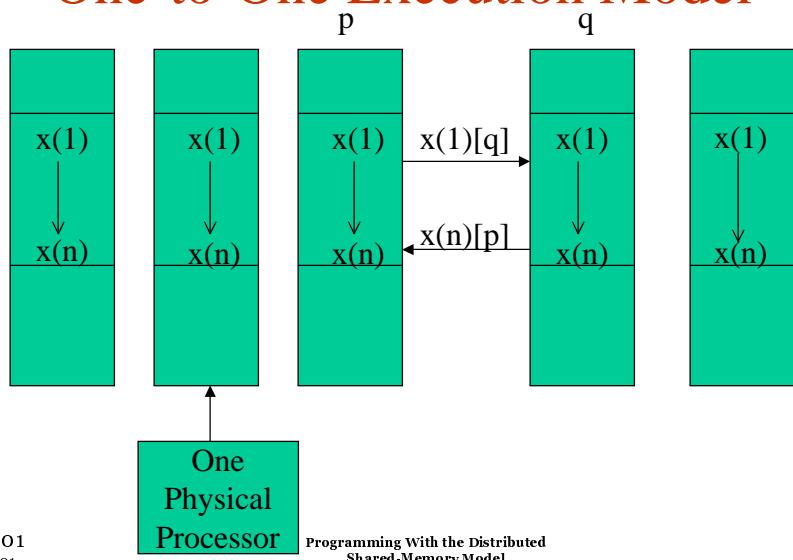
The Execution Model (II)

- Each image executes independently of the others.
- Communication between images takes place only through the use of explicit CAF syntax.
- The programmer inserts explicit synchronization as needed.

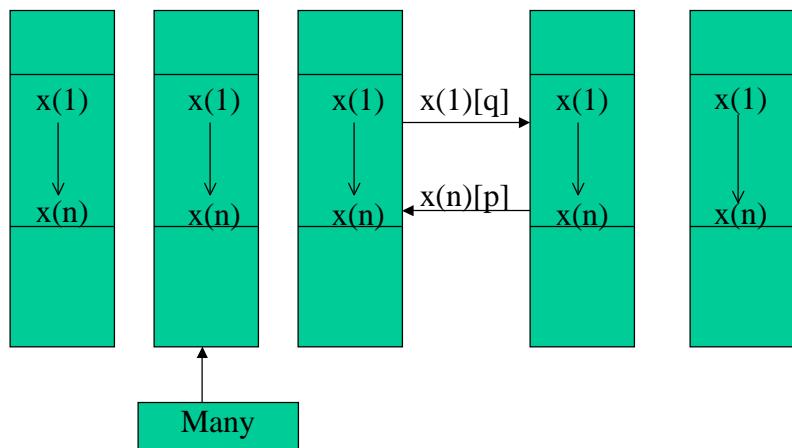
Who Builds the Map?

- The programmer specifies a **logical** map using co-array syntax.
- The underlying run-time system builds the **logical-to-virtual** map and a **virtual-to-physical** map.
- The programmer should be concerned with the logical map only.

One-to-One Execution Model



Many-to-One Execution Model

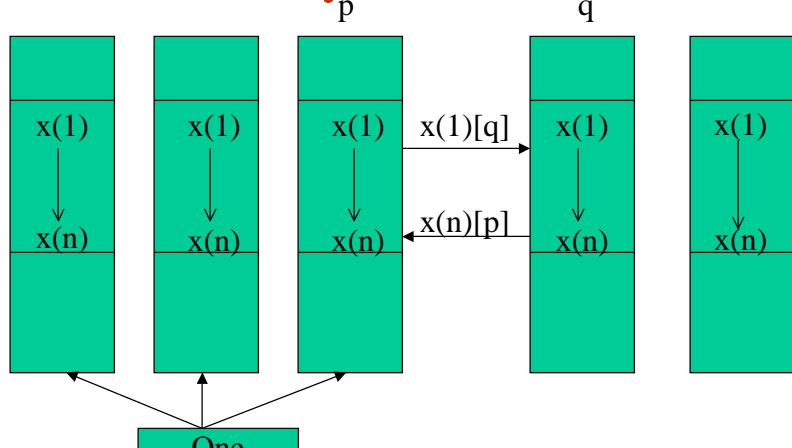


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One-to-Many Execution Model

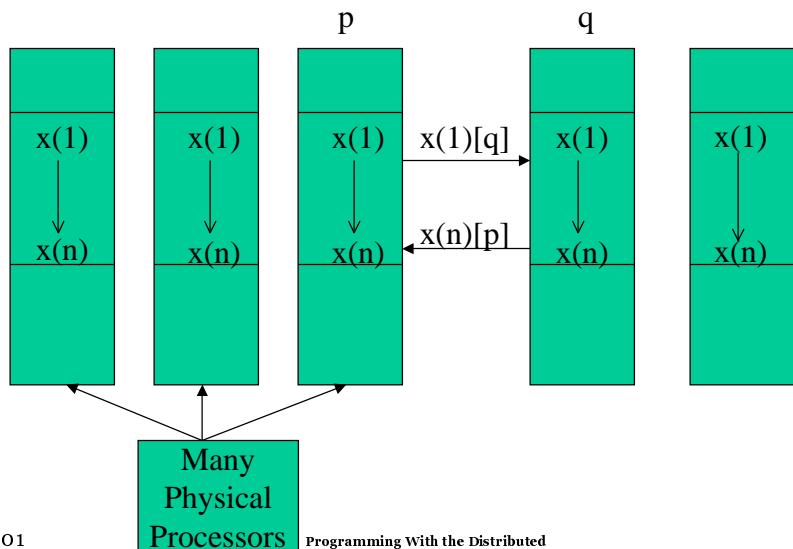


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Many-to-Many Execution Model



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4. Relative Image Indices

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Relative Image Indices

- Runtime system builds a map among images.
- CAF syntax is a *logical* expression of this map.
- Current image index:
`1 <= this_image() <= num_images()`
- Current image index relative to a co-array:
`lowCoBnd(x) <= this_image(x) <= upCoBnd(x)`

Relative Image Indices (1)

	1	2	3	4
1	1	5	9	13
2	2	6	10	14
3	3	7	11	15
4	4	8	12	16

`x[4,*]` `this_image() = 15` `this_image(x) = (/3,4/)`

Relative Image Indices (II)

	0	1	2	3
0	1	5	9	13
1	2	6	10	14
2	3	7	11	15
3	4	8	12	16

`x[0:3,0:*`] `this_image() = 15 this_image(x) = (/2,3/)`

Relative Image Indices (III)

	0	1	2	3
-5	1	5	9	13
-4	2	6	10	14
-3	3	7	11	15
-2	4	8	12	16

`x[-5:-2,0:*`] `this_image() = 15 this_image(x) = (-3, 3/)`

Relative Image Indices (IV)

		0	1	2	3	4	5	6	7	
		0	1	3	5	7	9	11	13	15
		1	2	4	6	8	10	12	14	16

`x[0:1,0:]*] this_image() = 15 this_image(x) = (0,7/)`

5. Synchronization

Synchronization Intrinsic Procedures

sync_all()

Full barrier; wait for all images before continuing.

sync_all(wait(:))

Partial barrier; wait only for those images in the wait(:) list.

sync_team(list(:))

Team barrier; only images in list(:) are involved.

sync_team(list(:),wait(:))

Team barrier; wait only for those images in the wait(:) list.

sync_team(myPartner)

Synchronize with one other image.

Events

sync_team(list(:),list(me:me)) post event

sync_team(list(:),list(you:you)) wait event

Example: Global Reduction

```
subroutine glb_dsum(x,n)
  real(kind=8),dimension(n)[0:] :: x
  real(kind=8),dimension(n)   :: wrk
  integer n,bit,i, mypartner, dim, me, m
  dim = log2_images()
  if(dim .eq. 0) return
  m = 2**dim
  bit = 1
  me = this_image(x)
  do i=1, dim
    mypartner=xor(me,bit)
    bit=shiftl(bit,1)
    call sync_all()
    wrk(:) = x(:)[mypartner]
    call sync_all()
    x(:)=x(:)+wrk(:)
  enddo
end subroutine glb_dsum
```

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Exercise: Global Reduction

- Convince yourself that two sync points are required.
- How would you modify the routine to handle non-power-of-two number of images?
- Can you rewrite the example using only one barrier?

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